# Team

ED Data Physics

A member of the  $\mathbf{N} \mathbf{v} \mathbf{\tau}$  GROUP



#### AGENDA



# **Discussion topics:**

- Test Method Comparison
- System Design
- CUBE System
- TENSOR System
- Method of Control

# Why M-DoF?

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- Replicating real-world excitations in the lab helps identify potentially new failure modes
- Can be a more accurate representation for drive input
- Higher fidelity testing leads to better product design and ultimately results in savings (cost, weight, etc.)



# TEST METHOD COMPARISON



- Simplest form of testing is 1-DoF
- M-DoF is now more common
- Realistic field representation
- Accelerated testing while maintaining fidelity
- M-DoF testing simultaneously leads to additional failure modes not captured in 1-DoF



#### TEST METHOD VISUAL: SETUP





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#### **TEST METHOD VISUAL**





#### **TEST METHOD VISUAL**





# MULTI AXIS SYSTEM DESIGN

- Multiple axes requires interconnection of many moving parts
- Kinematics are an important consideration
- Swivel-ends are low-cost solution
- Hydrostatic couplings offer high transmissibility
- High frequency requires stiffness







#### MULTI AXIS SYSTEM DESIGN

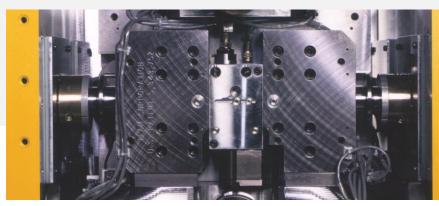




# CUBE TEST SYSTEM

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- CUBE is an integrated 6-DoF system
- Six double-ended, integrated actuators
- Hydrostatically supported table structure allows for 500 Hz response





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# **TEST METHOD VISUAL**

- 6-DoF system with tall payload running M-DoF random test
- Payload shifting around
- Road data simulating back of truck on a double-stack pallet load





# TENSOR TEST SYSTEM



- TENSOR is designed with ED shakers for a 2,000 Hz bandwidth
- Twelve oil-guided and oil-cooled
  ED shakers with integrated Pads
- Exceptional control over table
- Enhanced possibilities for multiaxis control





# CONTROL POSSIBILITIES

- Over-constrained design relies heavily on the test controller
- Improves control by maximizing connection to table structure
- Ability to control modeshapes in table using Matrix test controller

